

Python at Warp Speed

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Knowledge for Tomorrow



Introduction

Scientist,
Head of department



Deutsches Zentrum
für Luft- und Raumfahrt
German Aerospace Center

Co-Founder, Data
Scientist, and Patient

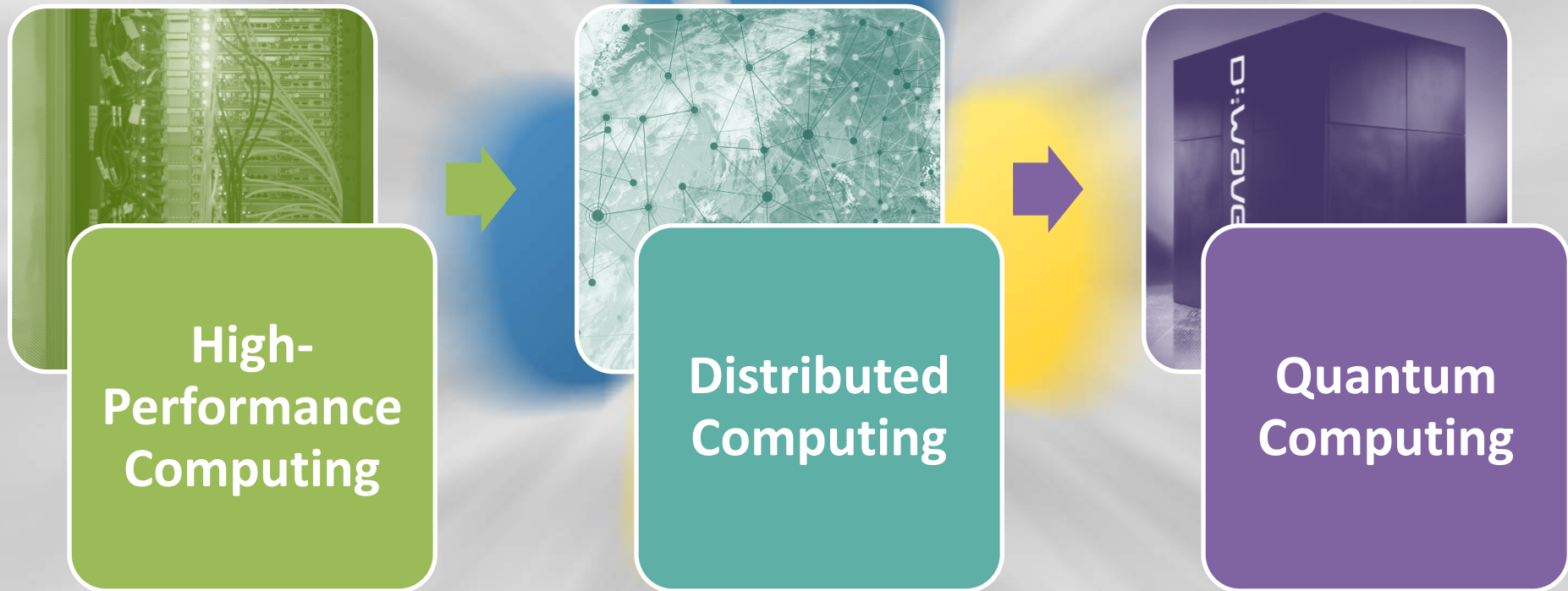


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Communities

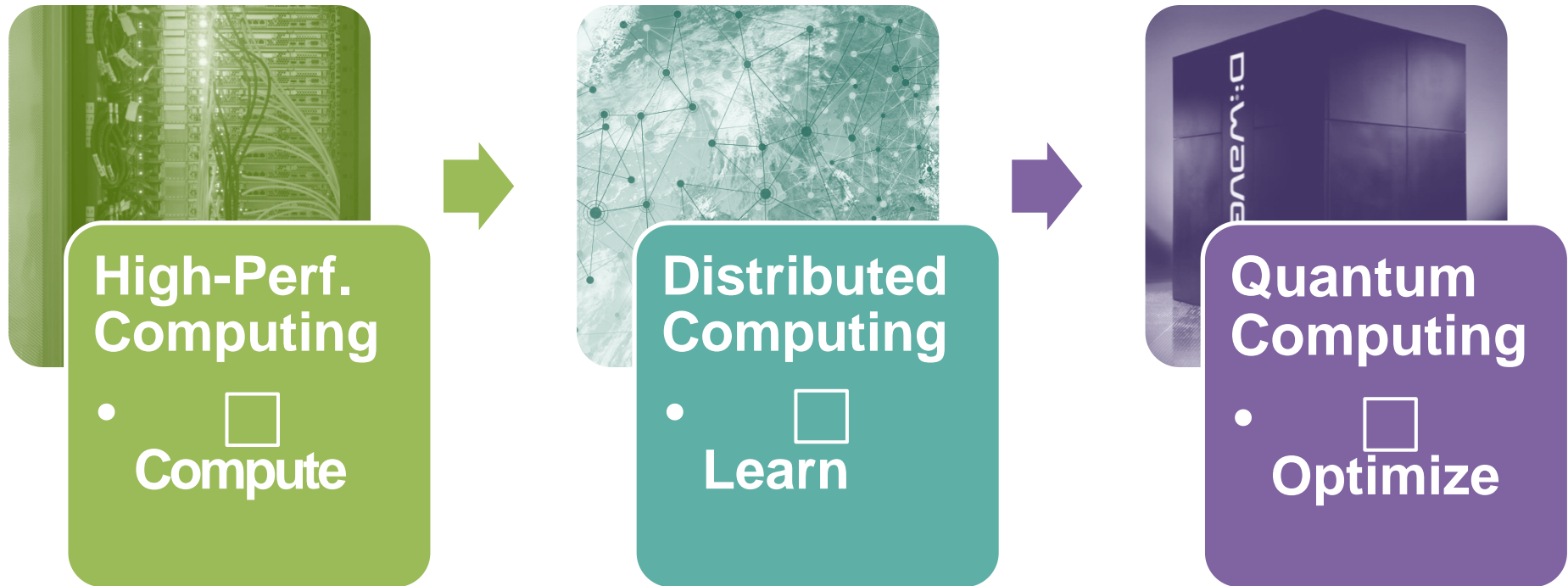


Python at Warp Speed



Algorithmic View

Input x – Algorithm \boxed{A} – Output y



High-Performance Computing

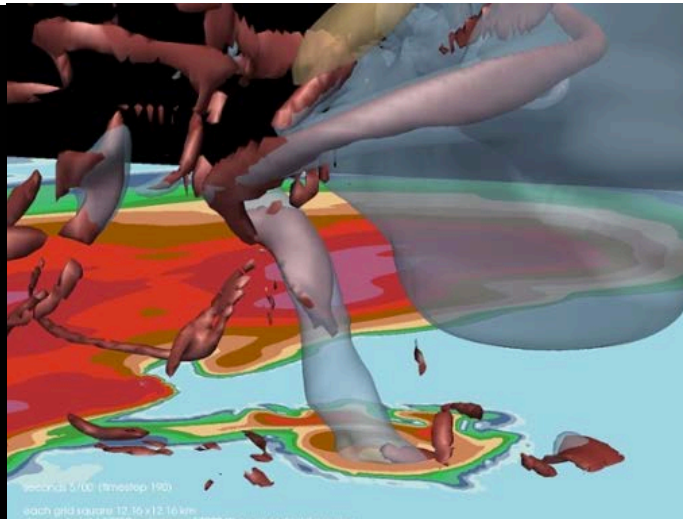
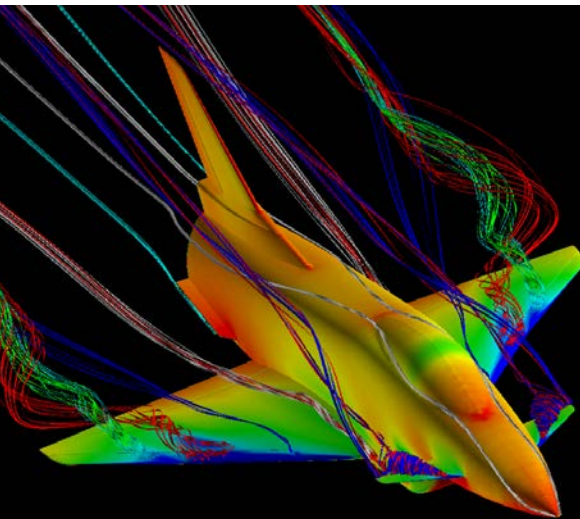


Knowledge for Tomorrow

High-Performance Computing

High raw computing power for large science applications

- Huge performance on a single / multi-core processors
- Huge machines with up to millions of cores



Sunway TaihuLight

10.649.600 Cores, 93 PetaFLOPS



Tianhe-2 (天河二号)

3.120.000 Cores, 33,8 PetaFLOPS



Titan

560.640 Cores, 17,5 PetaFLOPS



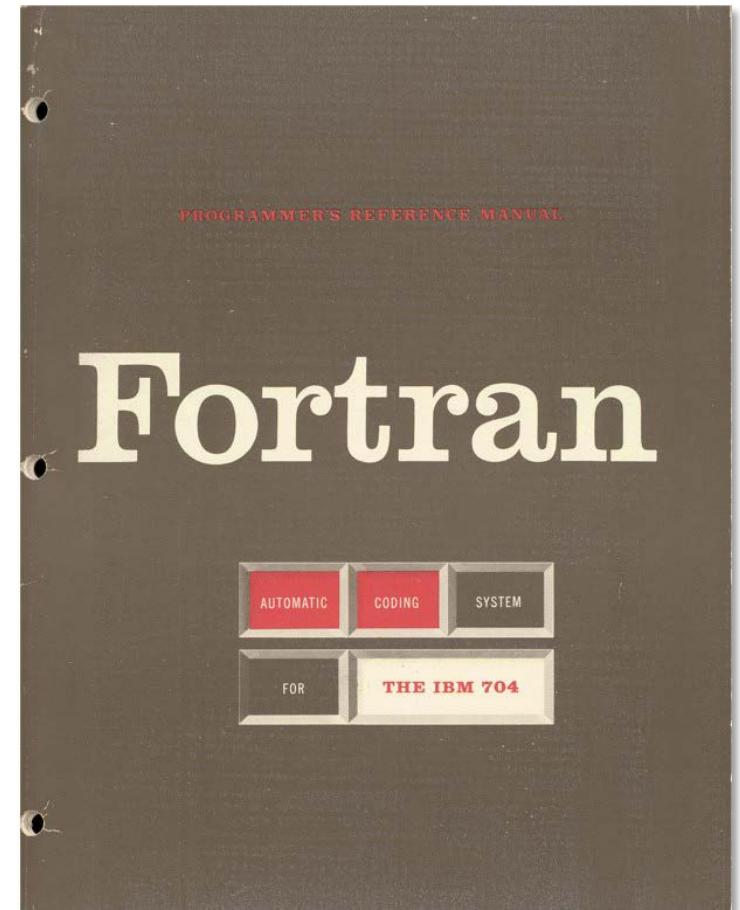
Programming HPC

Technologies

- MPI (Message Passing Interface)
- OpenMP (Open Multi-Processing)
- OpenACC (Open Accelerators)
- Global Arrays Toolkit
- CUDA (GPGPUs)
- OpenCL (GPGPUs)

Languages

- Fortran
- Fortran
- C/C++
- **Python**



Performance Fortran vs. Python

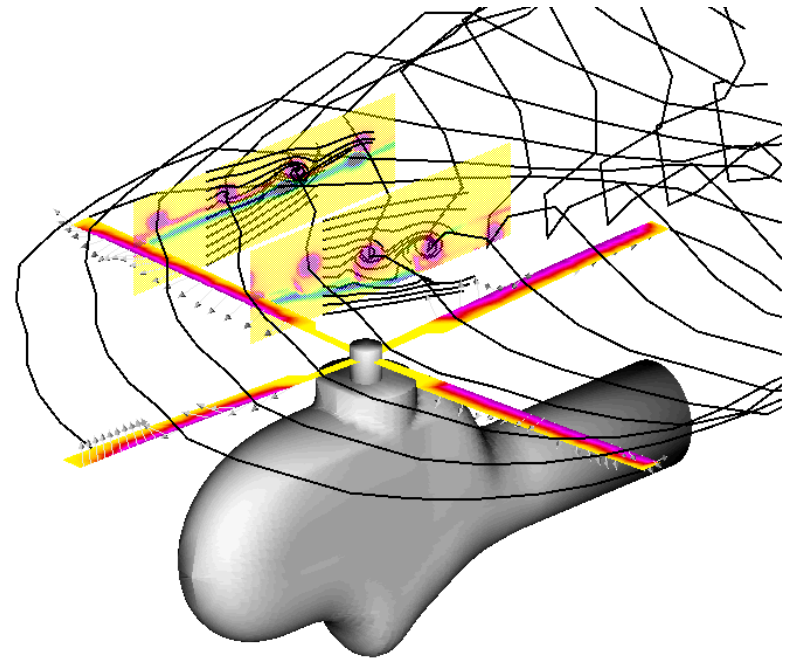
Helicopter Simulation

Fortran Code

- Developed 1994-1996
- parallelized with MPI
- Performance optimization 2013/14 with MPI und OpenACC

Performance Comparison

- Multi-core CPUs
 - Cython mit OpenMP
 - Python bindings for Global Array Toolkit
- GPGPUs
 - NumbaPro



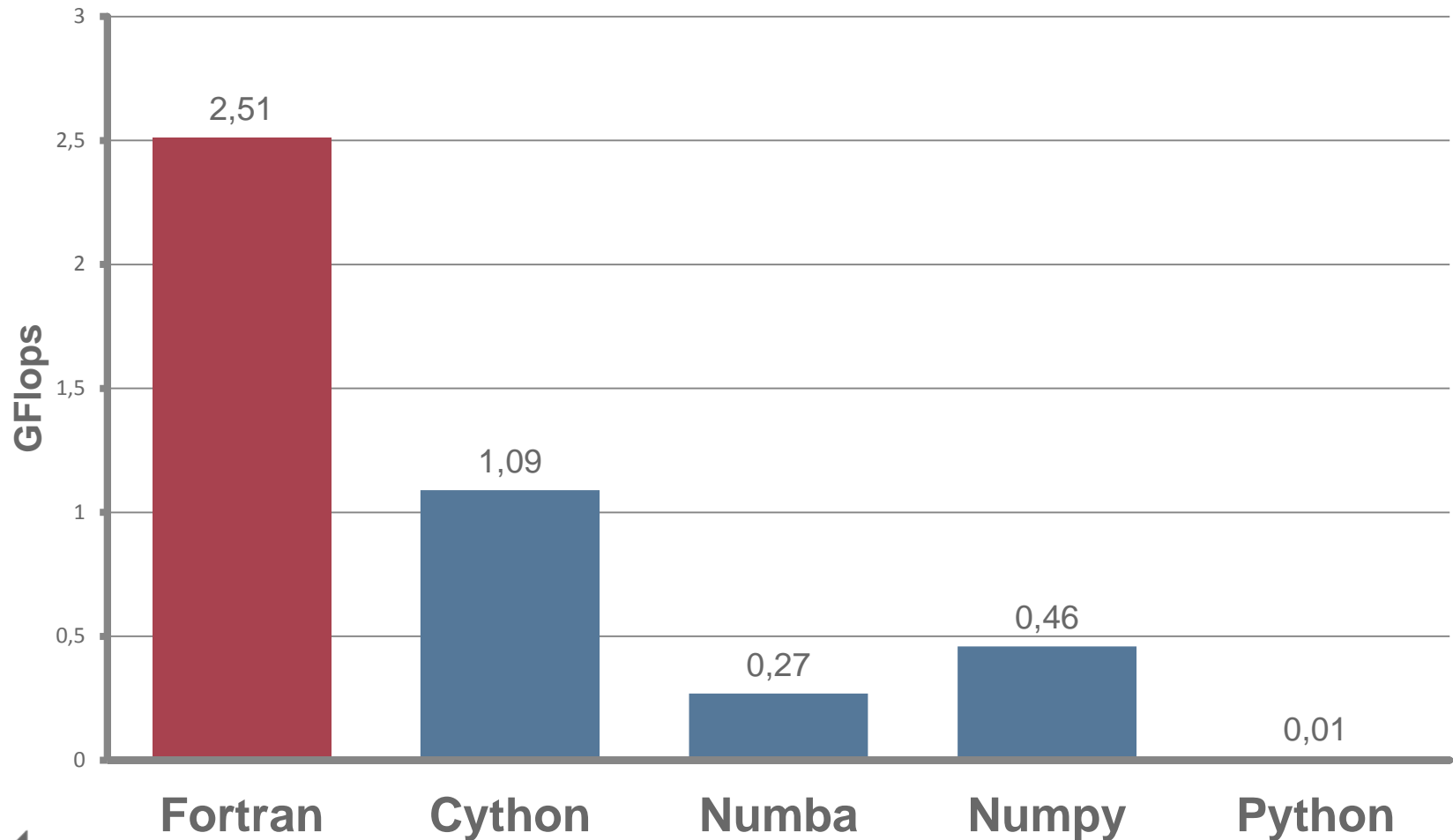
Core Computation Loops in Pure Python

```
for iblades in range(numberOfBlades):
    for iradial in range(1, dimensionInRadialDirection):
        for iazimutal in range(dimensionInAzimualDirectionTotal):
            for i1 in range(len(vx[0])):
                for i2 in range(len(vx[0][0])):
                    for i3 in range(len(vx[0][0][0])):
                        # wilin-Aufruf 1
for iblades in range(numberOfBlades):
    for iradial in range(dimensionInRadialDirection):
        for iazimutal in range(1, dimensionInAzimualDirectionTotal):
            for i1 in range(len(vx[0])):
                for i2 in range(len(vx[0][0])):
                    for i3 in range(len(vx[0][0][0])):
                        # wilin-Aufruf 2
for iDir in range(3):
    for i in range(numberOfBlades):
        for j in range(dimensionInRadialDirection):
            for k in range(dimensionInAzimualDirectionTotal):
                x[iDir][i][j][k] = x[iDir][i][j][k] +
                    dt * vx[iDir][i][j][k]
```



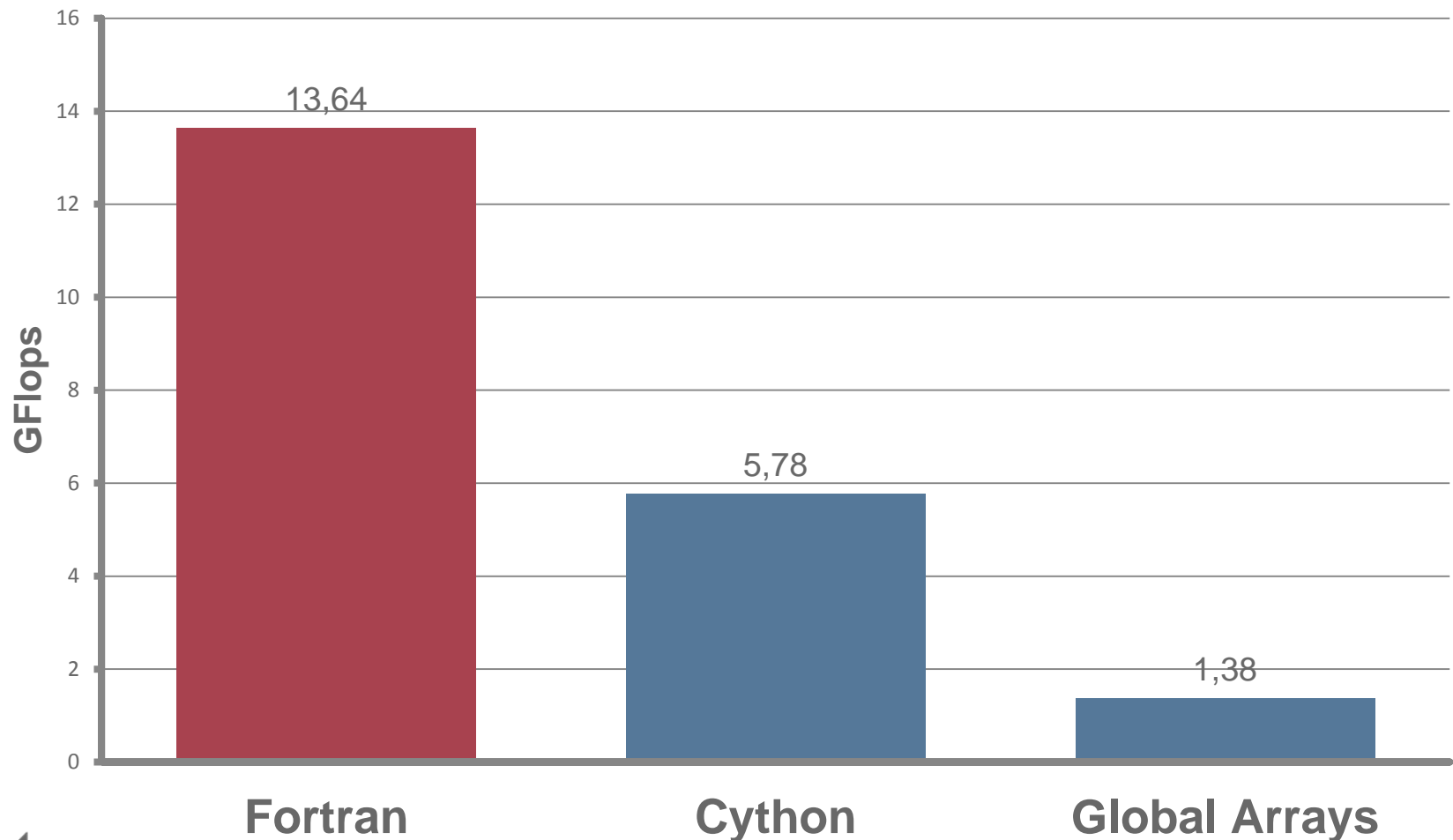
Performance Fortran vs. Python

Single Core (Xeon E5645, 6 Cores)



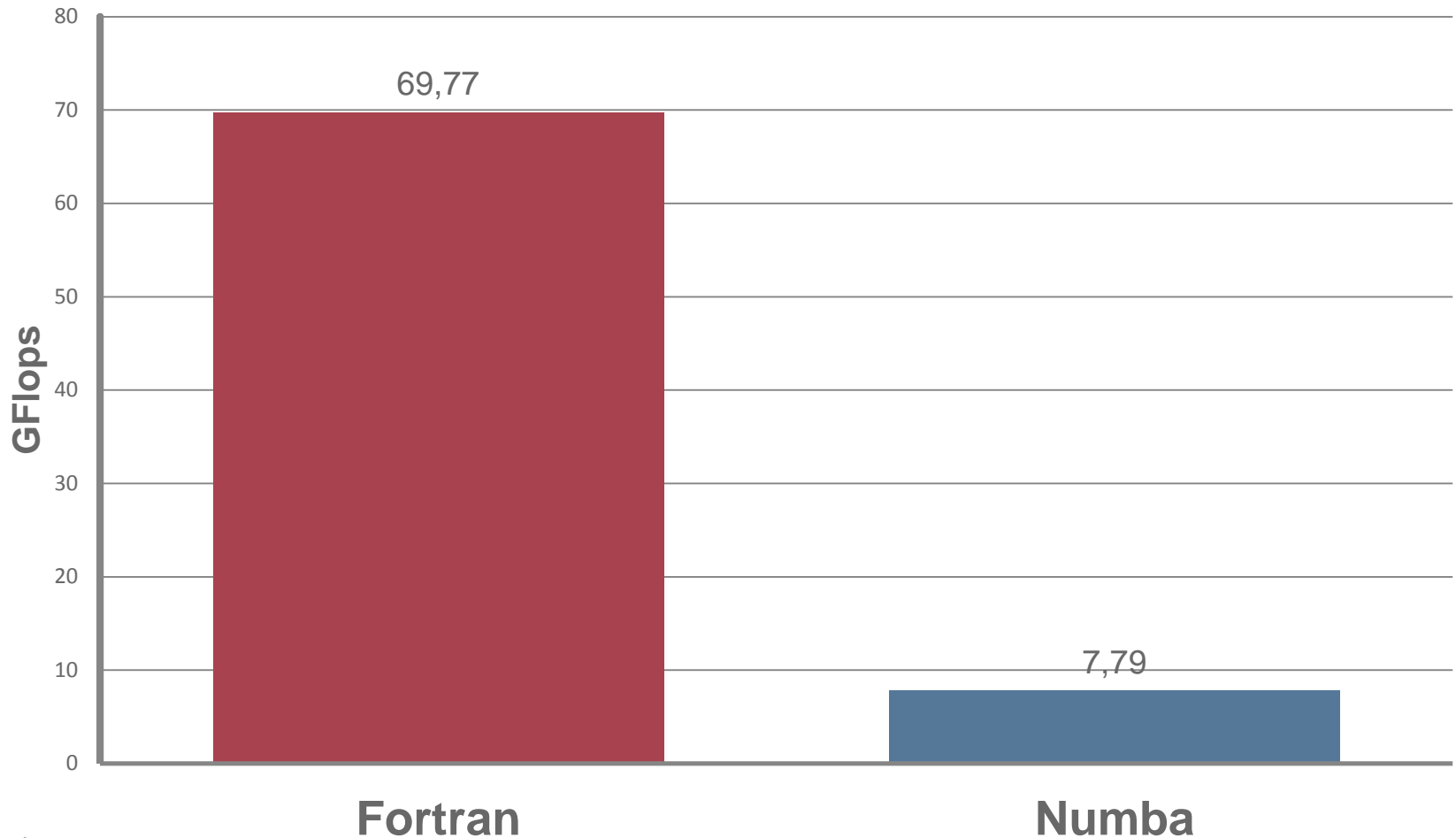
Performance Fortran vs. Python

Multi-Core (Xeon E5645, 6 Cores)

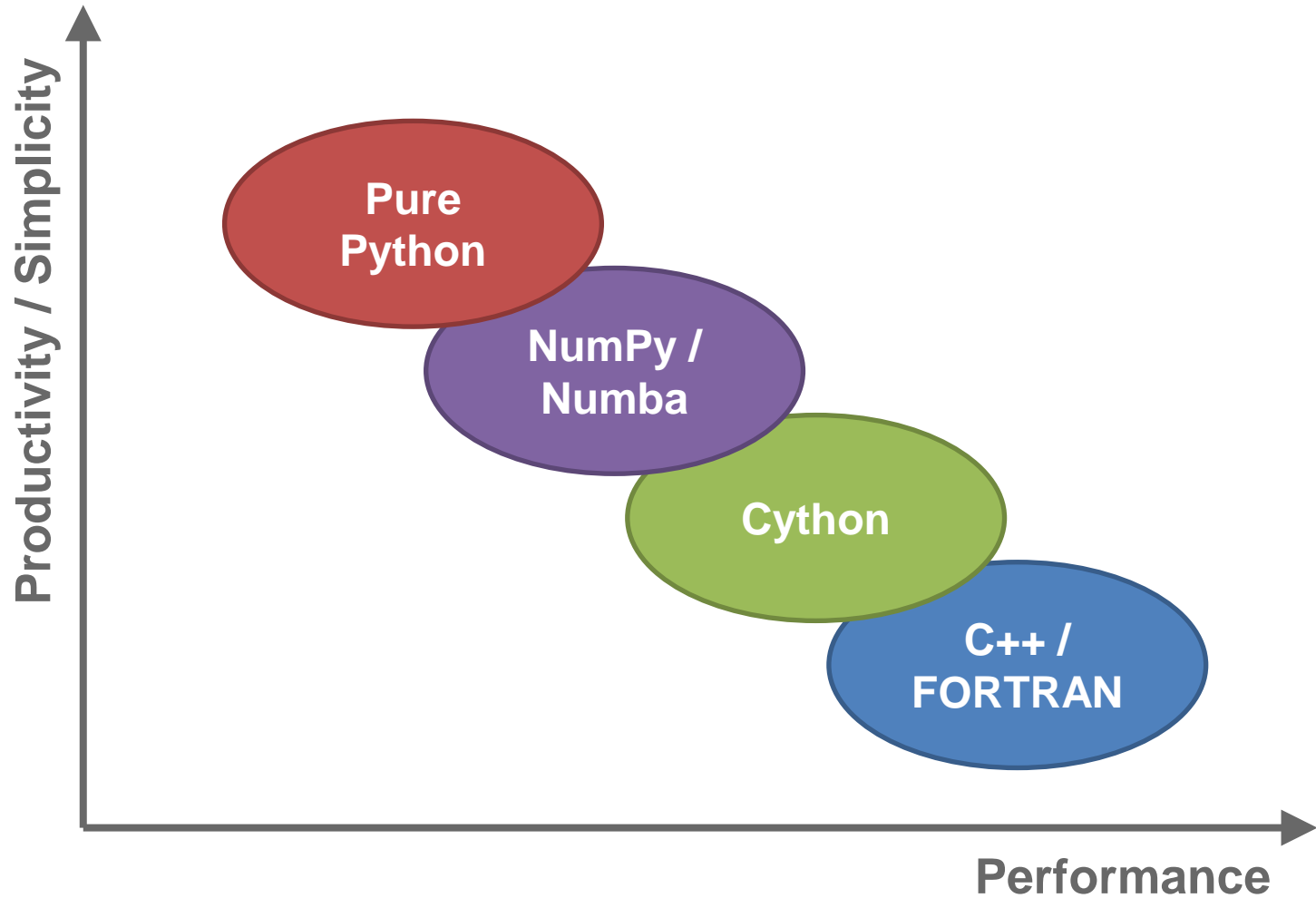


Performance Fortran vs. Python

GPGPU (NVIDIA Tesla C2075, 448 CUDA-Cores)



Performance-Productivity-Space



Productivity vs. Performance of Python

Python's productivity is great

- Allows to write code quickly
- Wide range of applications

Python's performance still needs improvements

- Code optimization with tools for profiling, code examination, ...
- Optimized libraries for parallel processing with MPI etc.

Excited to see advancements by community and companies



Workshop „Python for High-Performance and Scientific Computing“ (PyHPC)

Annual scientific workshop, in conjunction with Supercomputing conference

State-of-the-art in

- Hybrid programming
- Comparison with other languages for HPC
- Interactive parallel computing
- High-performance computing applications
- Performance analysis, profiling, and debugging

PyHPC 2016

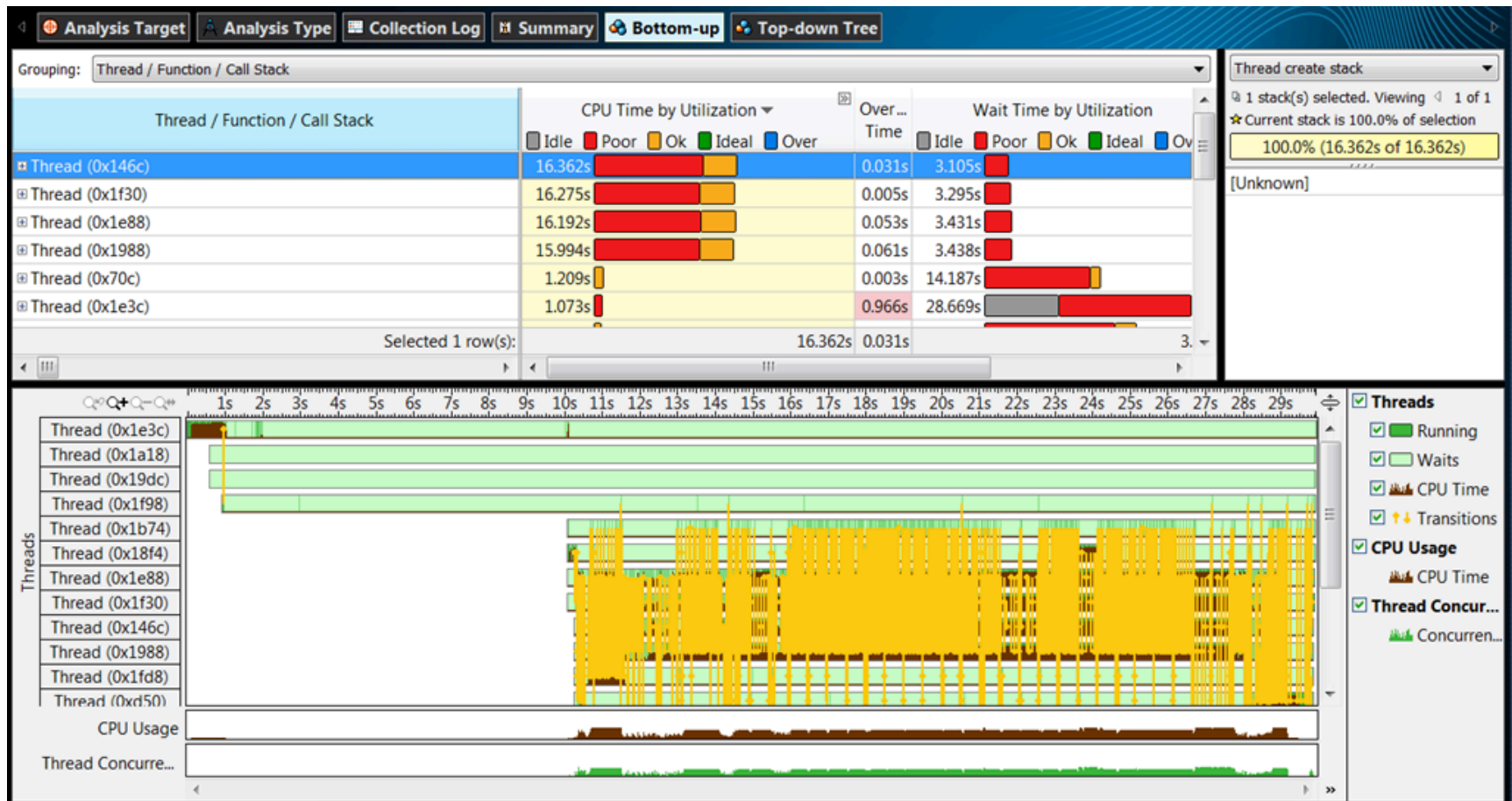
- 6th edition, Nov 14, 2016, Salt Lake City
- <http://www.dlr.de/sc/pyhpc2016>





Tools Example

Intel® VTune™ Amplifier for Profiling



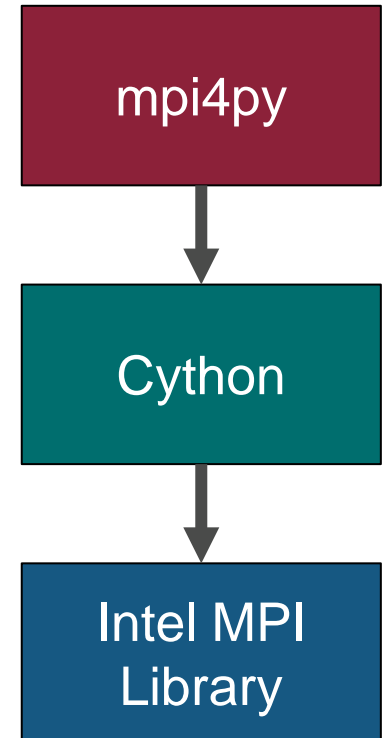
<https://software.intel.com/en-us/intel-vtune-amplifier-xe/>

Tools Example

mpi4py with Intel MPI Library and Cython



```
from mpi4py import MPI
comm = MPI.COMM_WORLD
size = comm.Get_size()
rank = comm.Get_rank()
name = MPI.Get_processor_name()
if rank == 0:
    print "Rank %d of %d running on %s"
        % (rank, size, name)
    for i in xrange(1, size):
        rank, size, name = comm.recv(source=i, tag=1)
        print "Rank %d of %d running on %s"
            % (rank, size, name)
else:
    comm.send((rank, size, name), dest=0, tag=1)
```



<http://pythonhosted.org/mpi4py/>

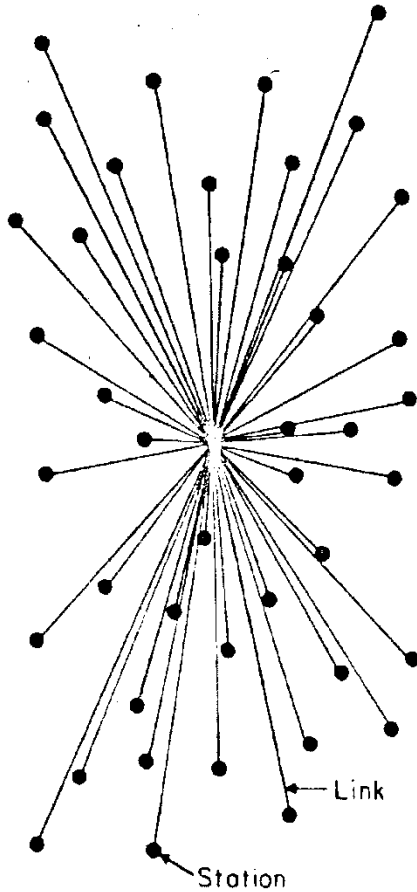
<https://software.intel.com/en-us/intel-mpi-library>

Distributed Computing

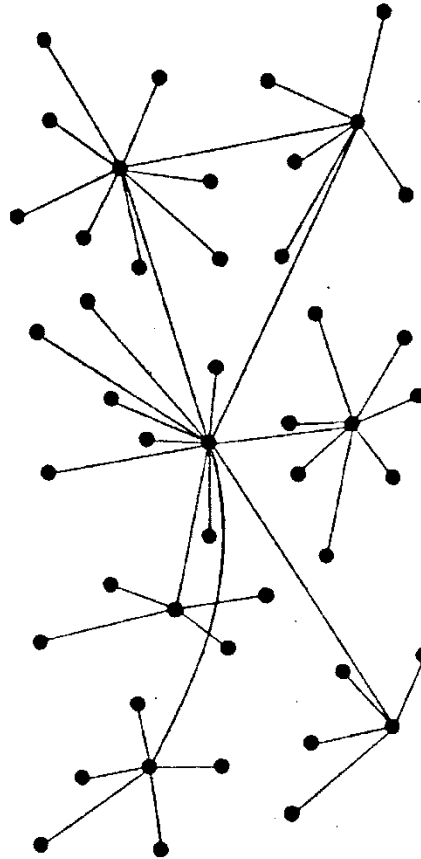


Knowledge for Tomorrow

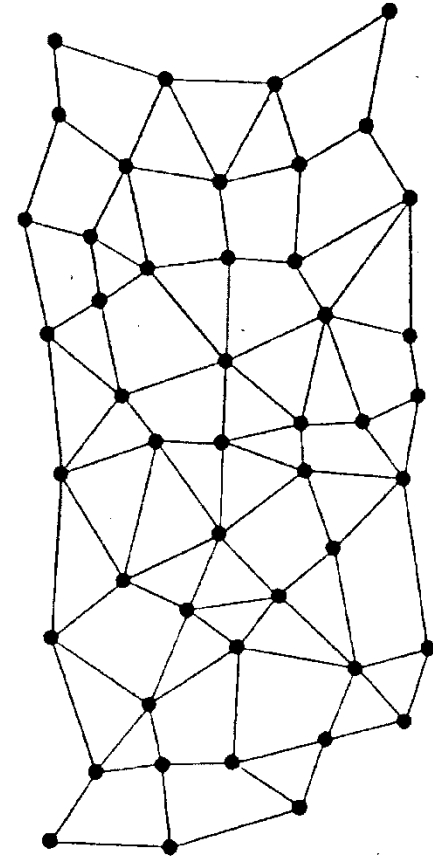
Distributed Computing



CENTRALIZED
(A)



DECENTRALIZED
(B)



DISTRIBUTED
(C)

Distributed Computing

Driven by data science, machine learning, predictive analytics, ...

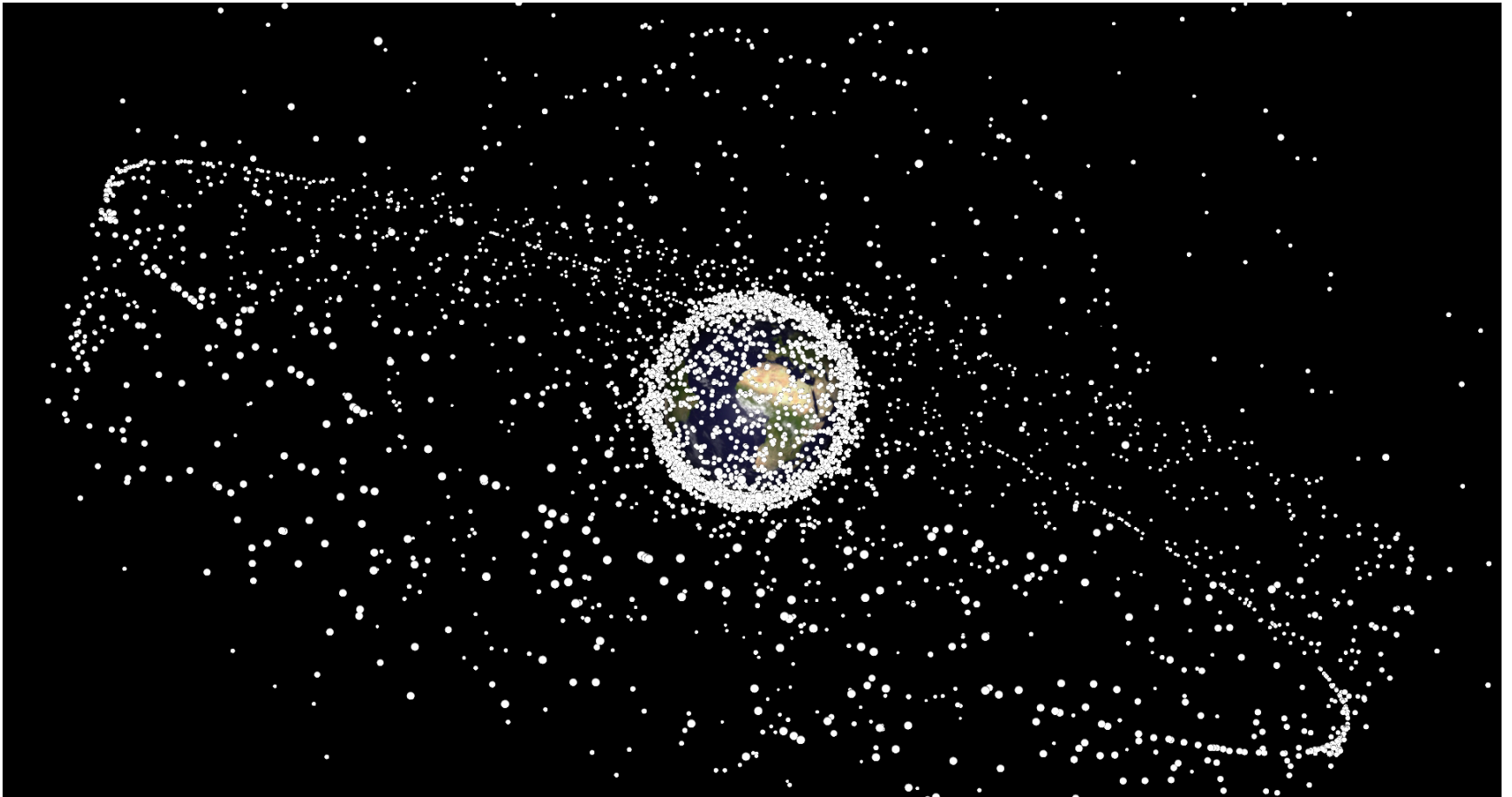
- Tabular data
- Time Series
- Stream data
- Connected data

**Scaling up with increased data size
from from laptops to clusters**

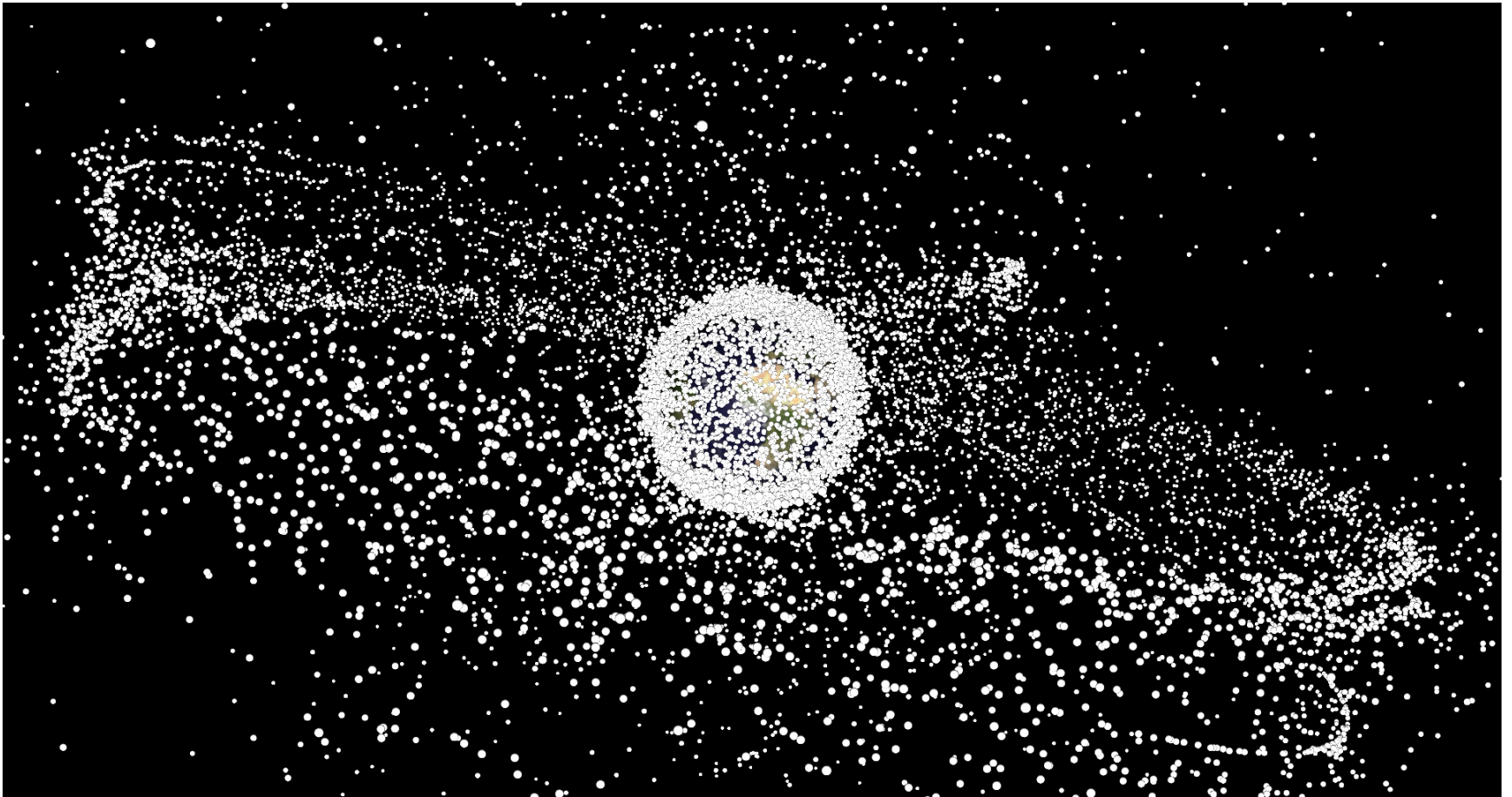
- Many-Task-Computing
- Distributed scheduling
- Peer-to-peer data sharing:



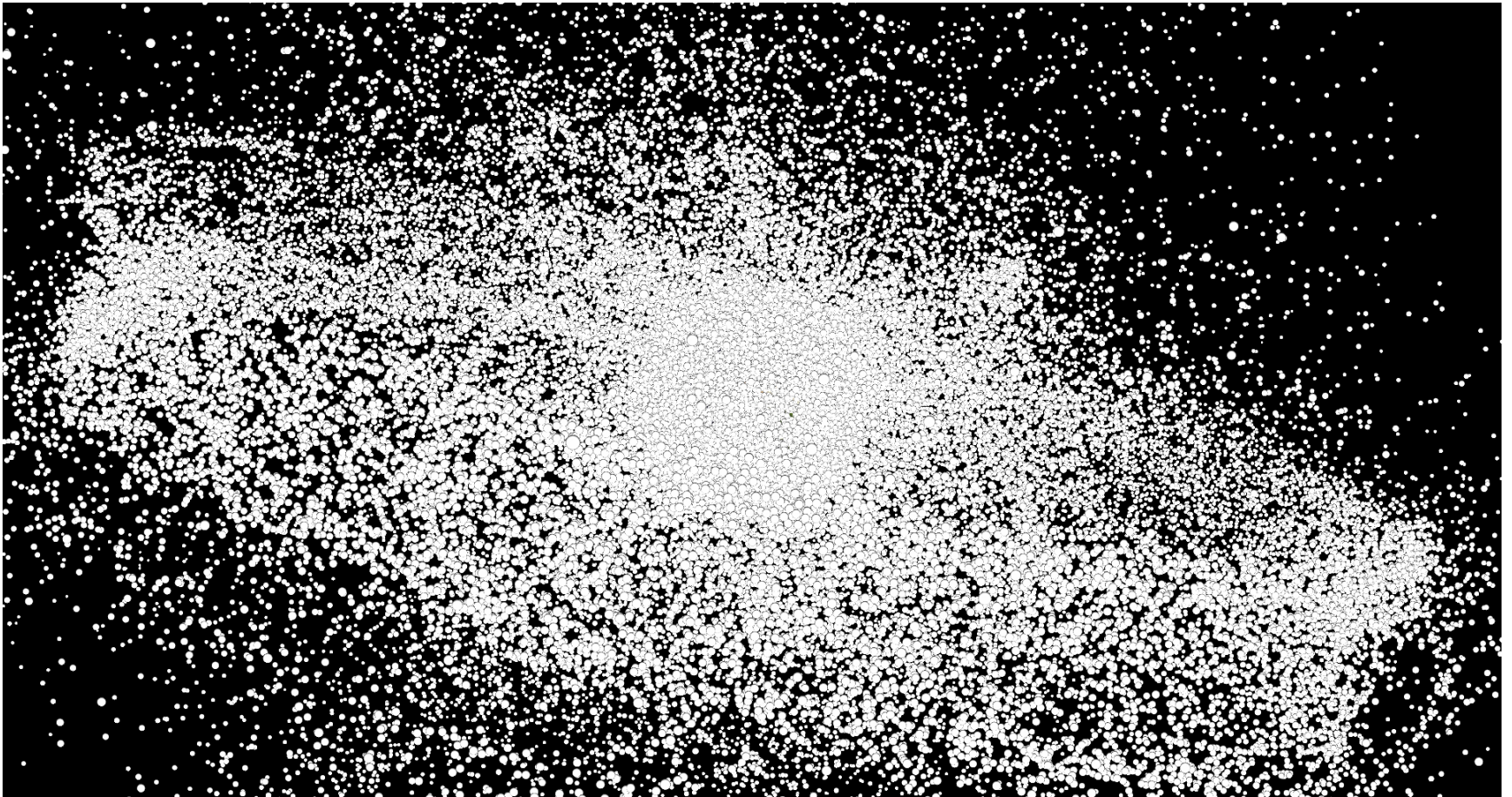
Space Debris: Object Correlation from Sensor Data and Real-Time Collision Detection



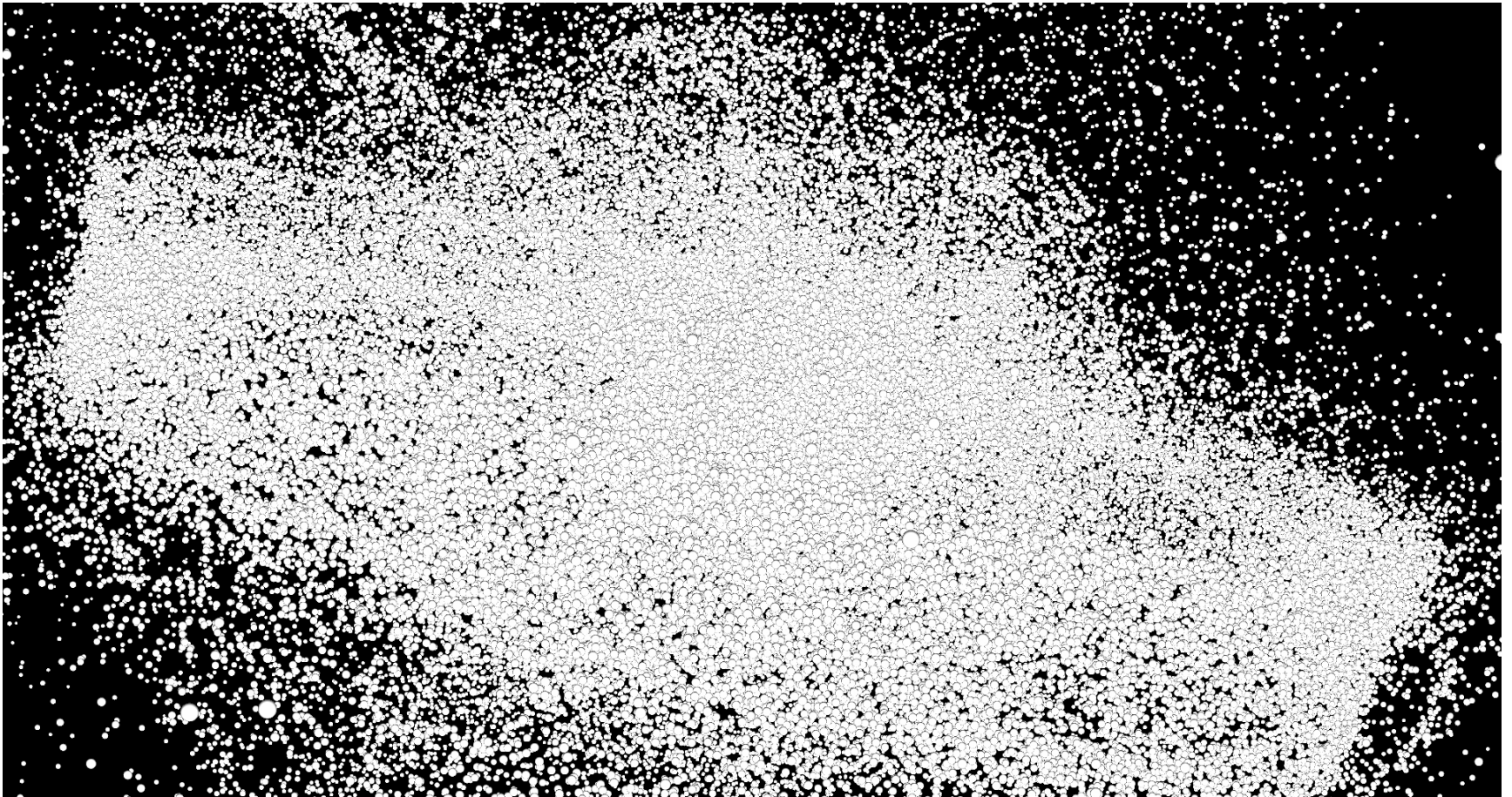
29,000 Objects Larger than 10 cm



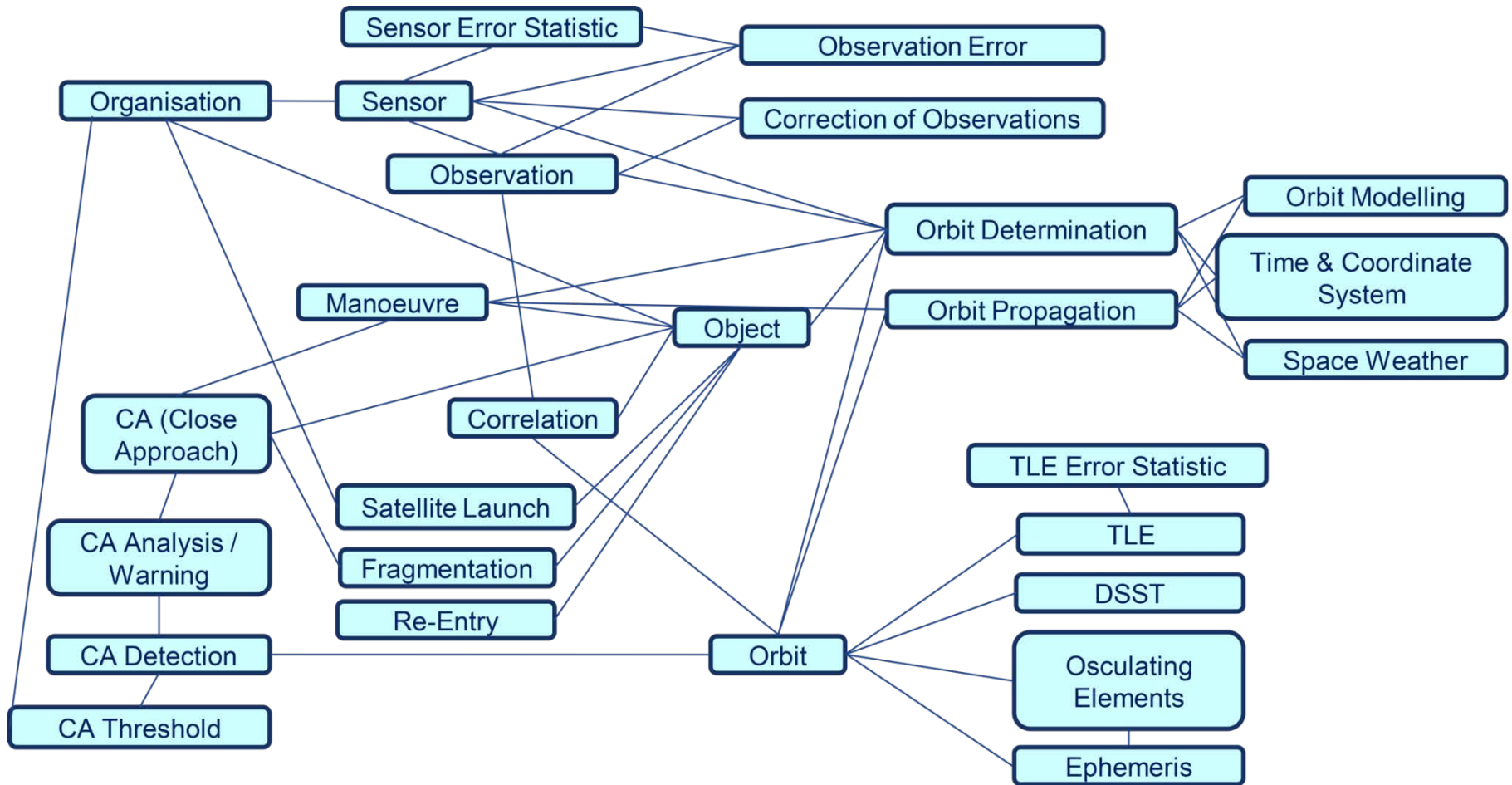
750,000 Objects Larger than 1 cm



150M Objects Larger than 1 mm

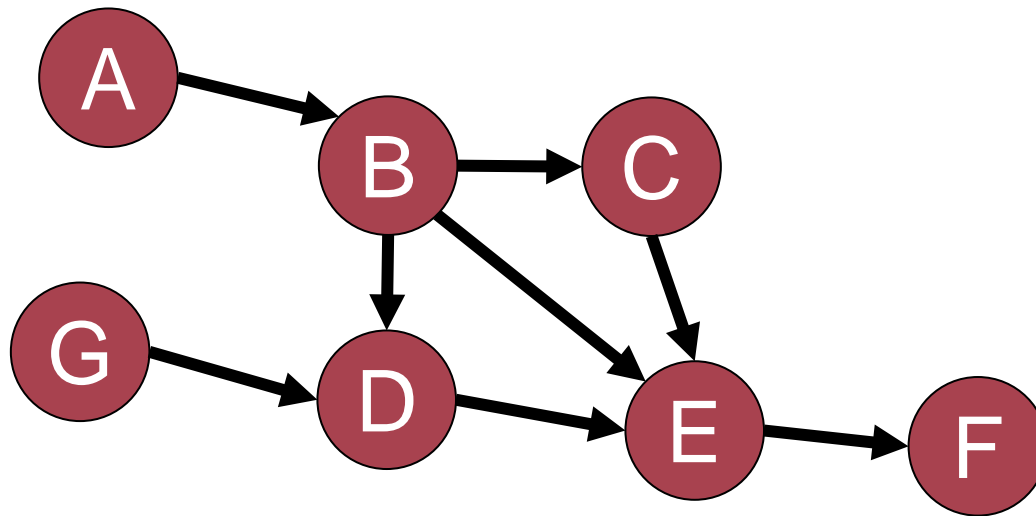


Space Debris: Graph of Computations



Graphs

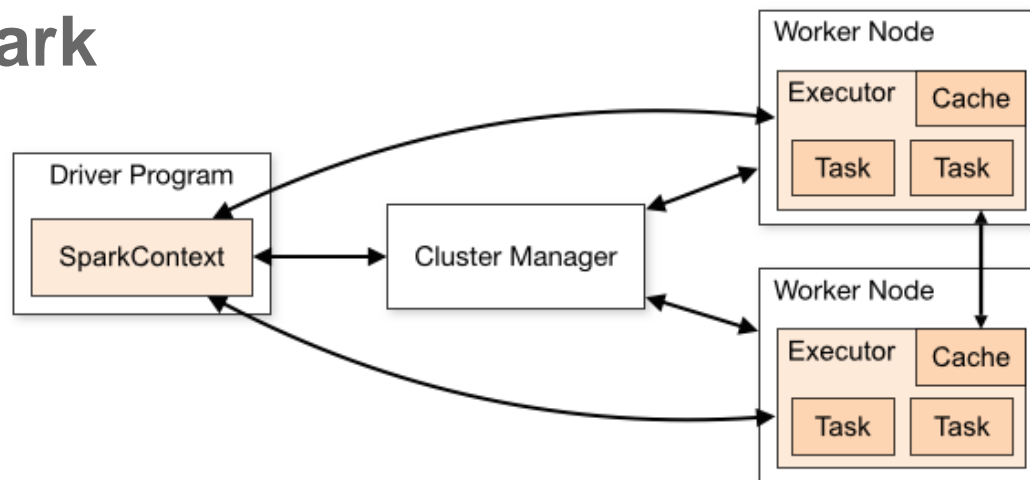
Directed Acyclic Graph (DAG)



Python has great tools to execute graphs on distributed resources



PySpark



```
from pyspark import SparkContext
```

```
logFile = "myfile.txt"
```

```
sc = SparkContext("local", "Simple App")
```

```
logData = sc.textFile(logFile).cache()
```

```
numAs = logData.filter(lambda s: 'a' in s).count()
```

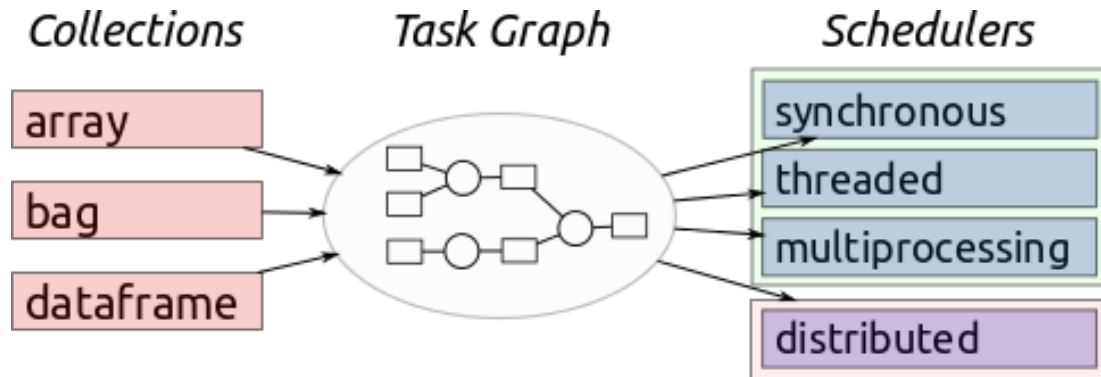
```
numBs = logData.filter(lambda s: 'b' in s).count()
```

```
print("Lines with a: %i, lines with b: %i" % (numAs, numBs))
```

<https://spark.apache.org/>

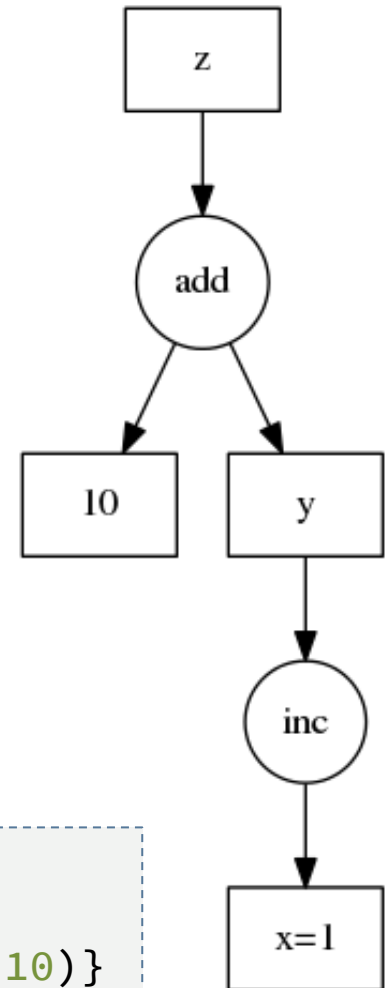
<https://spark.apache.org/docs/0.9.0/python-programming-guide.html>

Dask



```
import dask.dataframe as dd
df = dd.read_csv('2015-*-*.csv')
df.groupby(df.user_id).value.mean().compute()
```

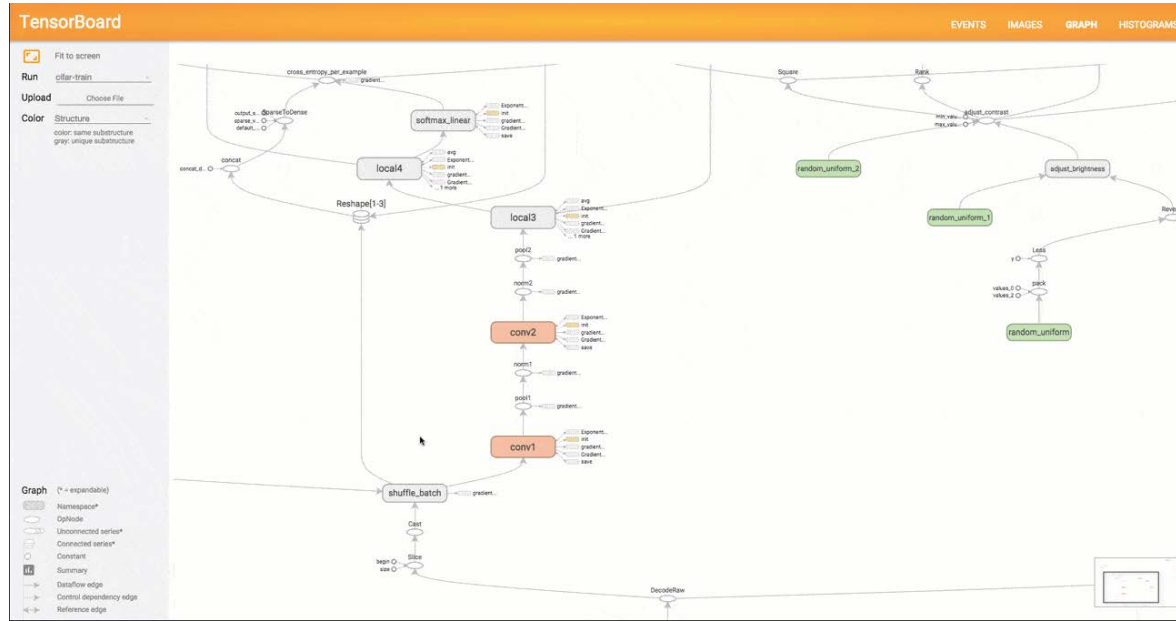
```
d = {'x': 1,
     'y': (inc, 'x'),
     'z': (add, 'y', 10)}
```



<http://dask.pydata.org/>



TensorFlow



```
import tensorflow as tf
```

```
with tf.Session() as sess:
    with tf.device("/gpu:1"):
        matrix1 = tf.constant([[3., 3.]])
        matrix2 = tf.constant([[2.], [2.]])
        product = tf.matmul(matrix1, matrix2)
```

<https://www.tensorflow.org/>



Quantum Computing

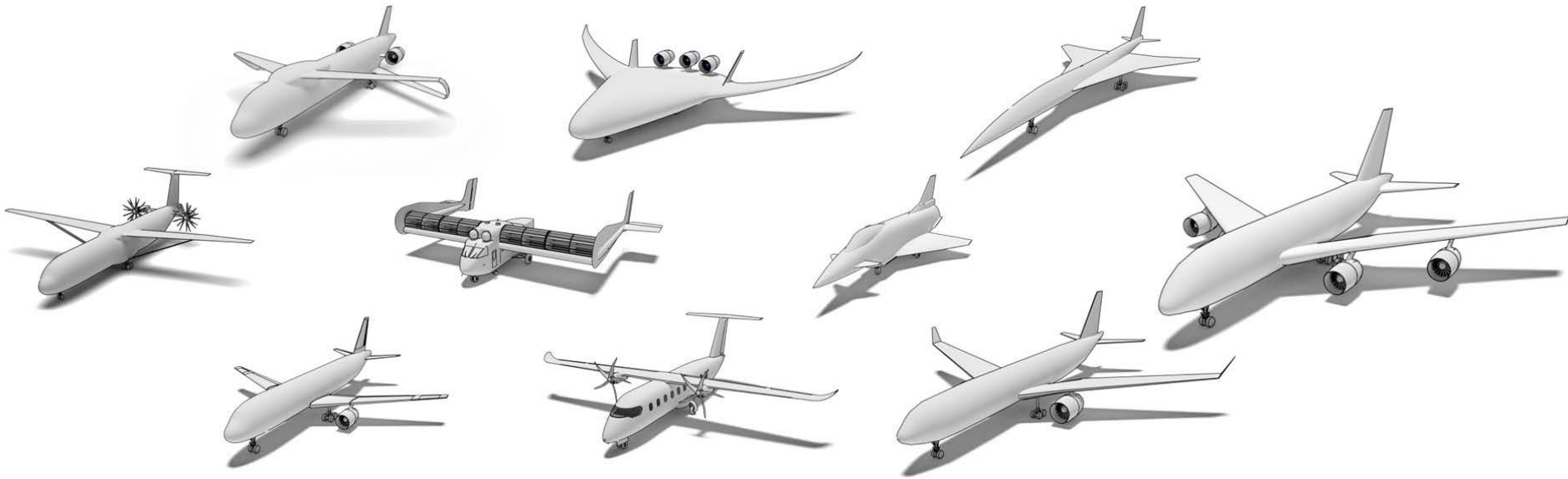


Knowledge for Tomorrow

Optimization Problems in Aeronautics & Space

Design optimization and robust design

- Space systems and air transportation systems
- Design and evaluation of systems with consideration of uncertainties



Optimization Problems in Aeronautics & Space

Machine Learning

- Deep learning, pattern recognition, clustering, images recognition, stream reasoning

Anomaly detection

- Monitoring of space systems

Mission planning

- Optimization in relation to time, resource allocation, energy consumption, costs etc.

Verification and validation

- Software, embedded systems



New Research Field: Quantum Computing

Discrete optimization is basis for many kinds of problems

- Packaging
- Partitioning
- Mapping
- Scheduling

NP-hard problems!

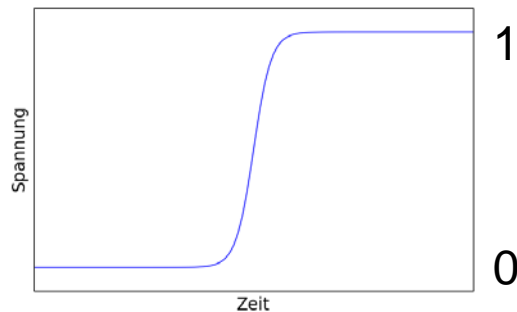
Hope: **Quantum Computers** solve those problems faster than classical computers



Bits and Qubits

Classical Bits

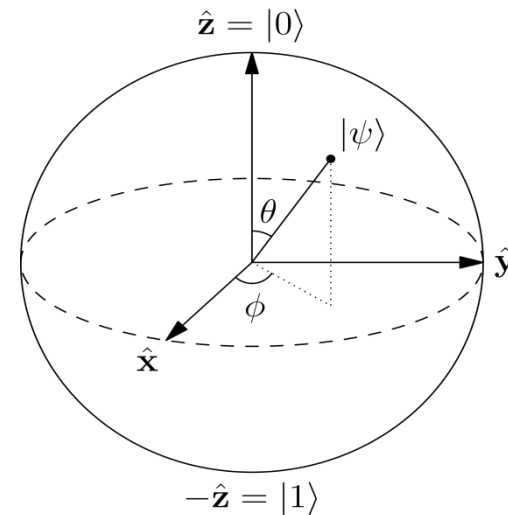
- “0” or “1”
- Electric voltage



Quantum bits (Qubits)

- Superposition of complex base states

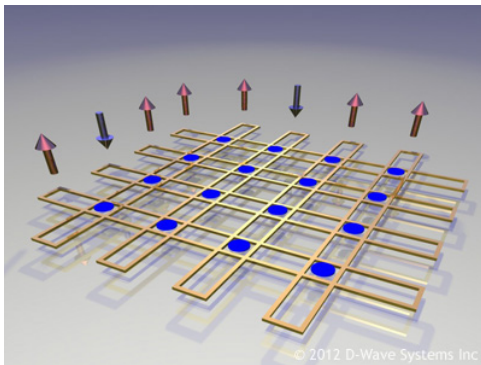
$$|\psi\rangle = c_0|0\rangle + c_1|1\rangle$$

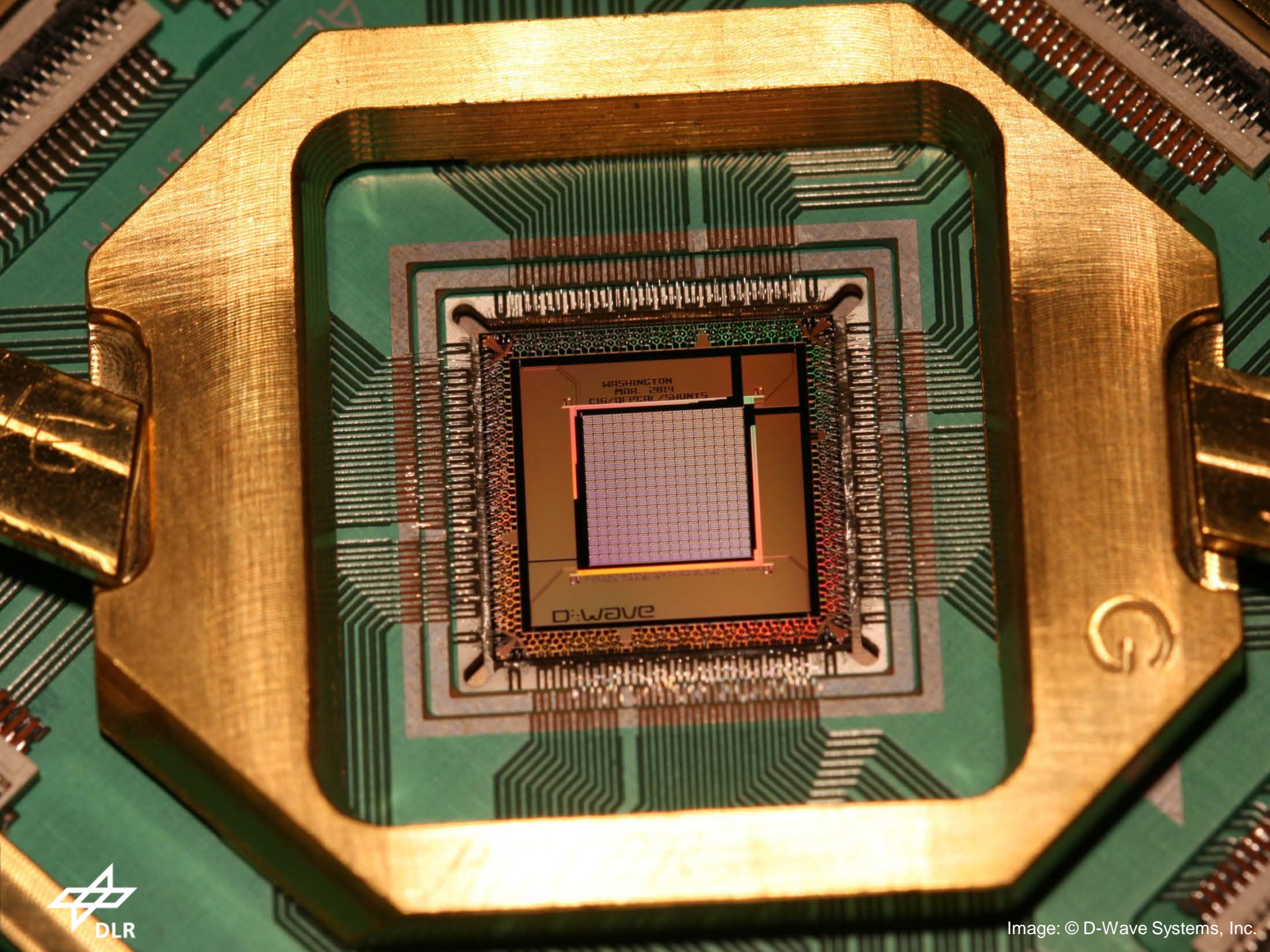


Quantum Computer

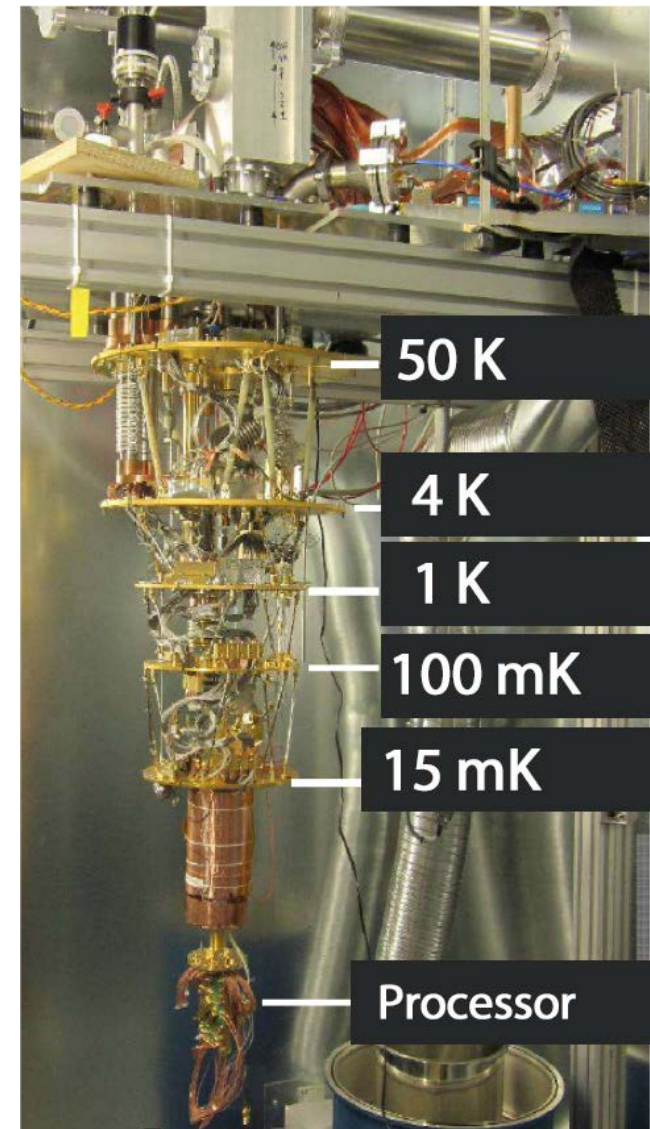
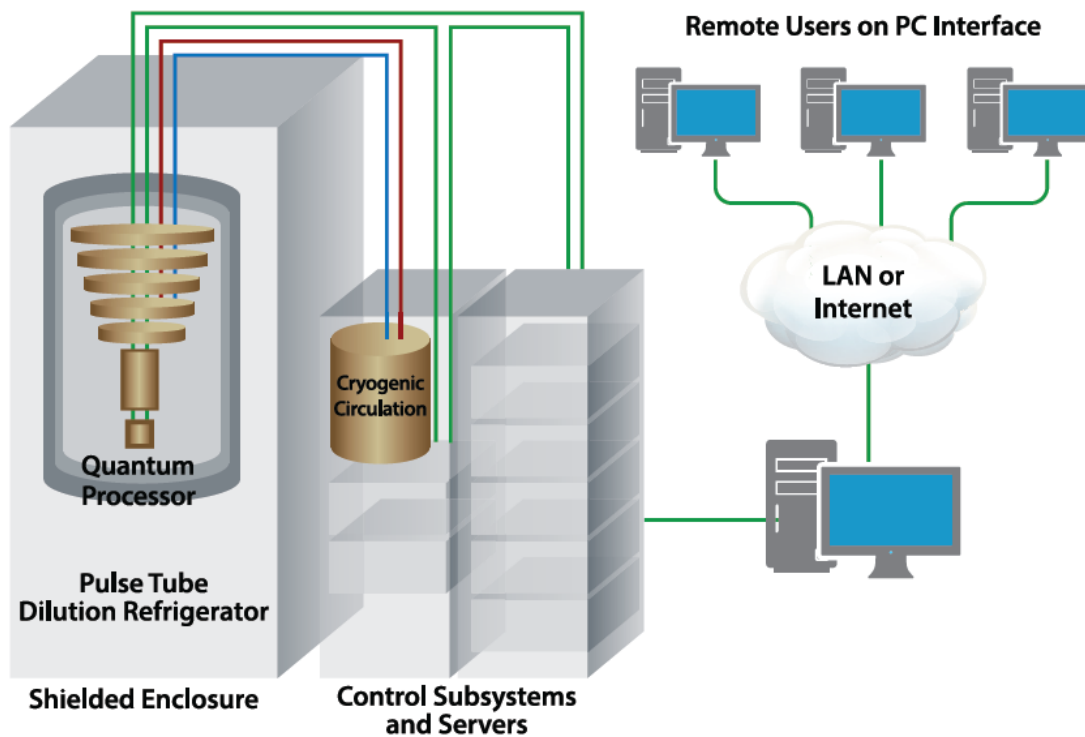
To date, one Quantum Computer is available commercially

- D-Wave Systems, Inc., Canada
- System with ~2000 Qubits („D-Wave 2X“)
- Adiabatic QC

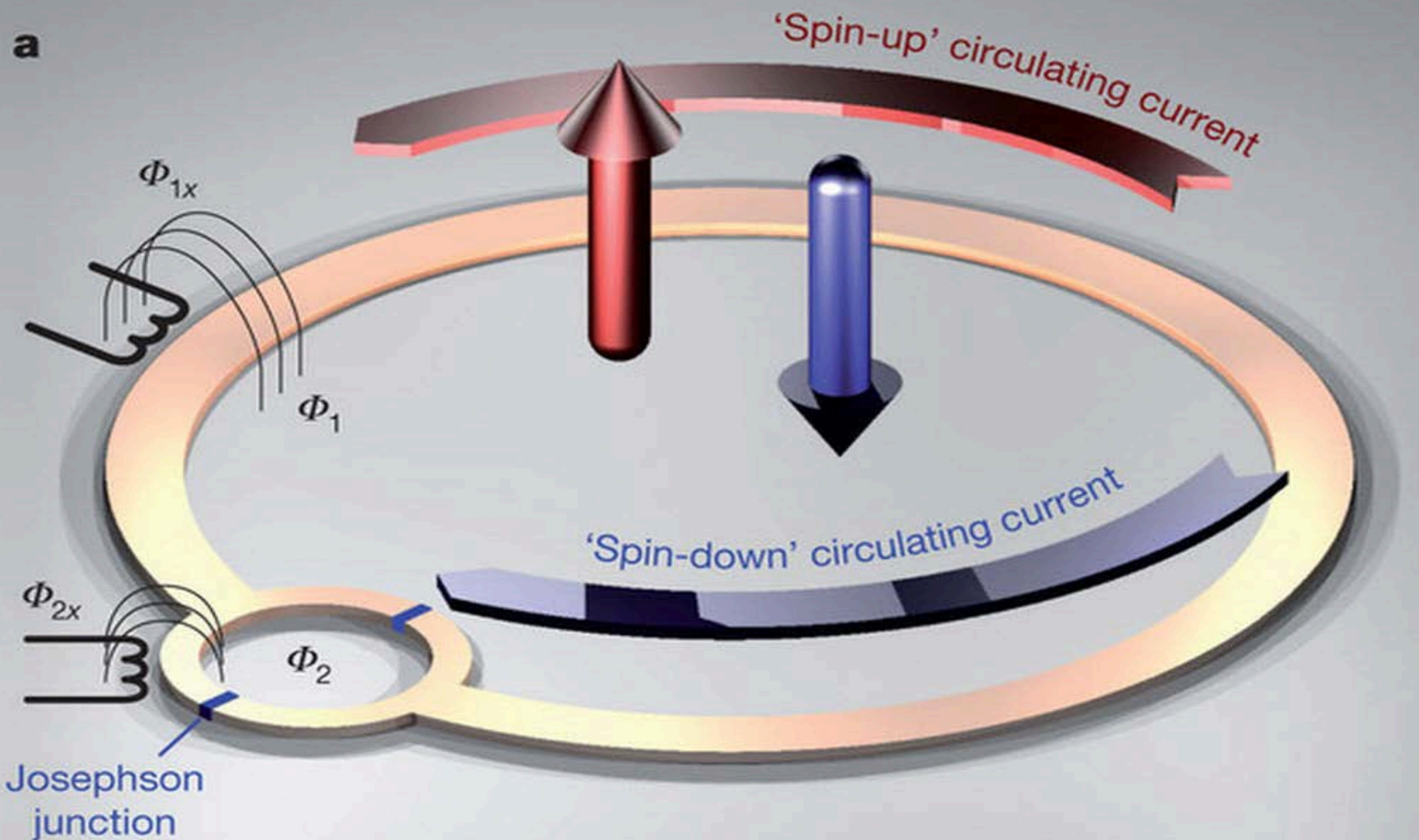




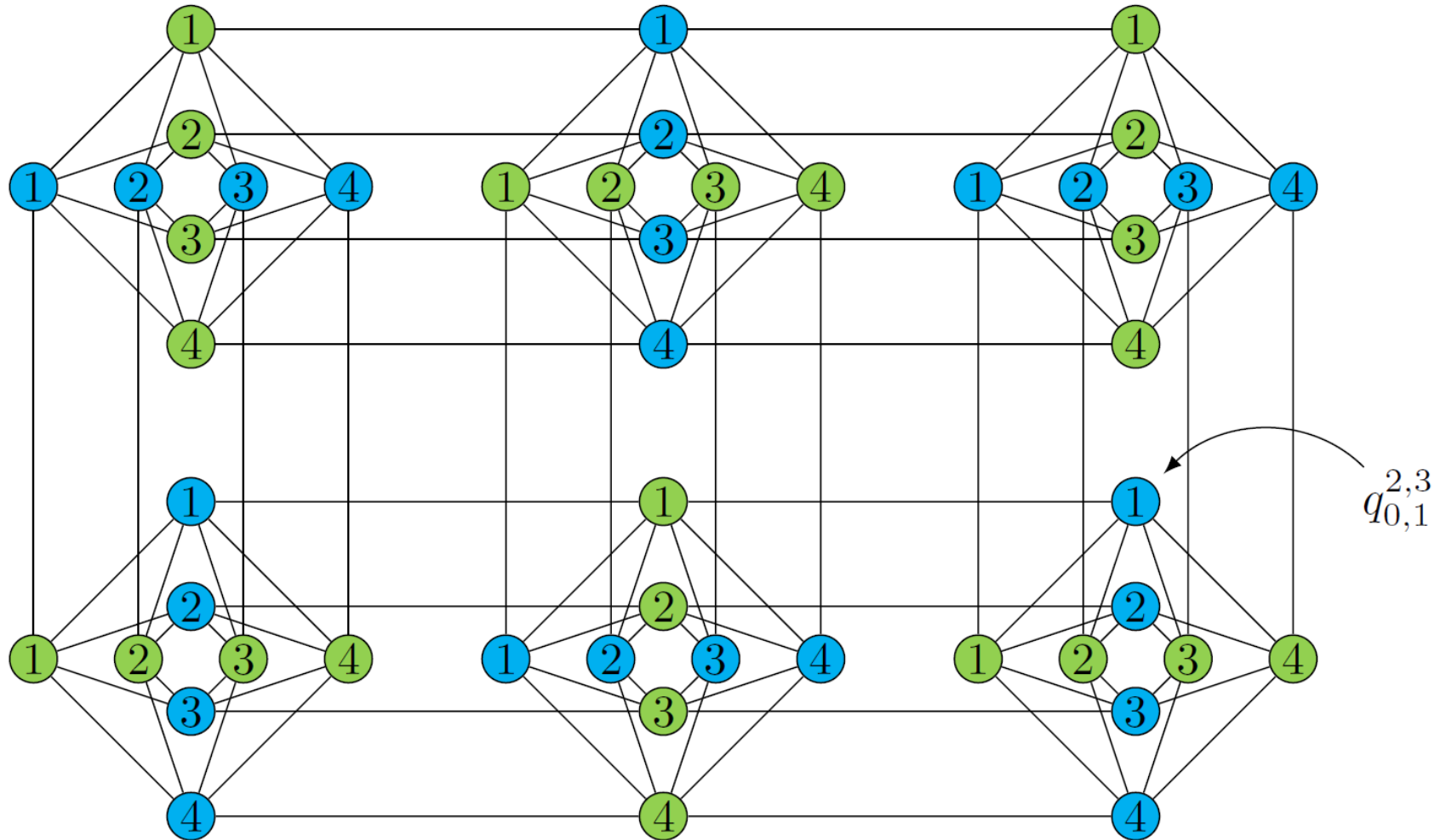
Inside D-Wave 2



Images: © D-Wave Systems, Inc.



D-Wave Qubit Topology – Chimera Graph



“Programming” a Quantum Computer – Step 1

Rewrite the problem as discrete optimization problem

- **QUBO**: Quadratic unconstrained binary optimization

$$E(q_1, \dots, q_n) = \sum_{i=1}^n g_i q_i + \sum_{\substack{i,j=1 \\ i>j}}^n s_{ij} q_i q_j$$

$$q_i = \begin{cases} 0, & \text{for switch off} \\ 1, & \text{for switch on} \end{cases}$$

g_i weights

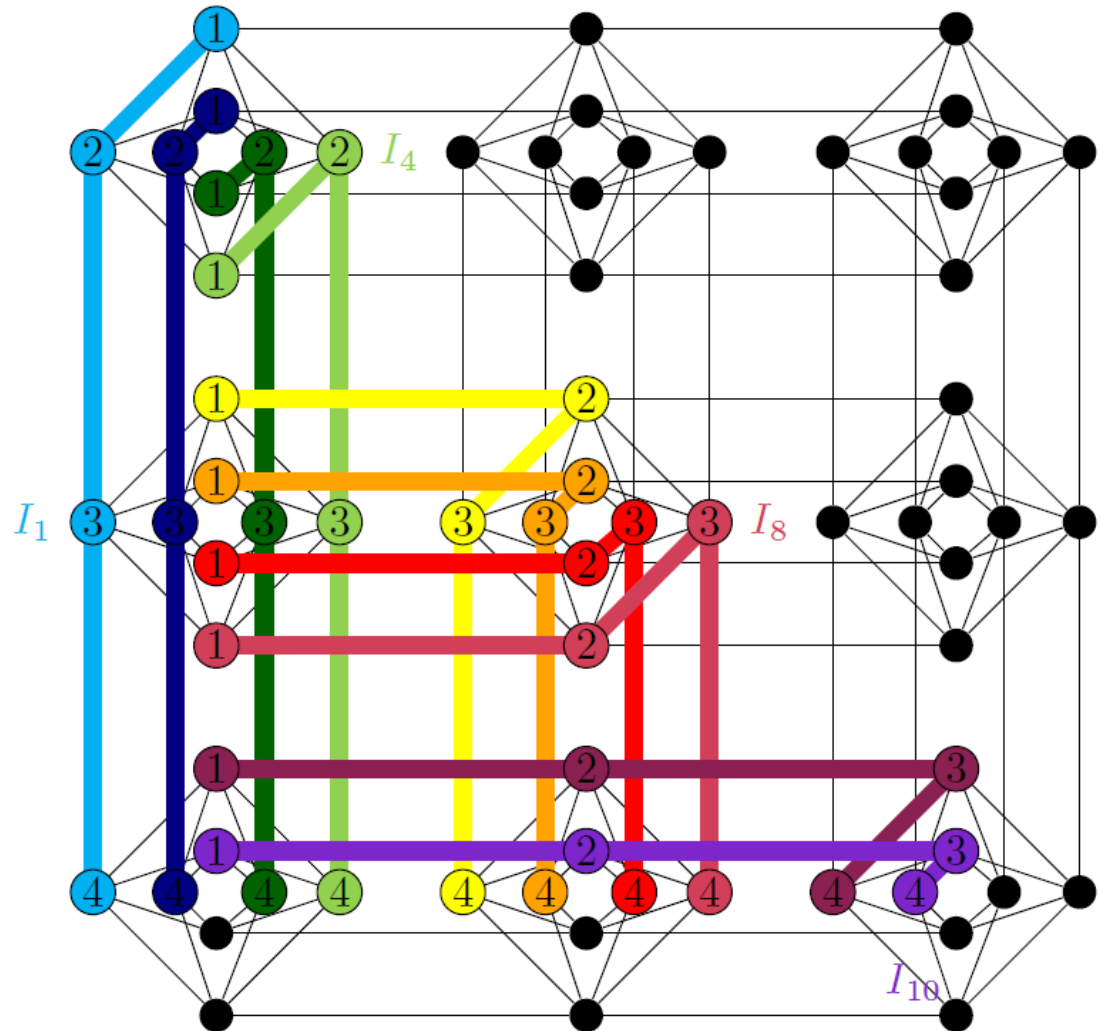
s_{ij} strength of coupling



“Programming” a Quantum Computer – Step 2

Mapping to hardware topology

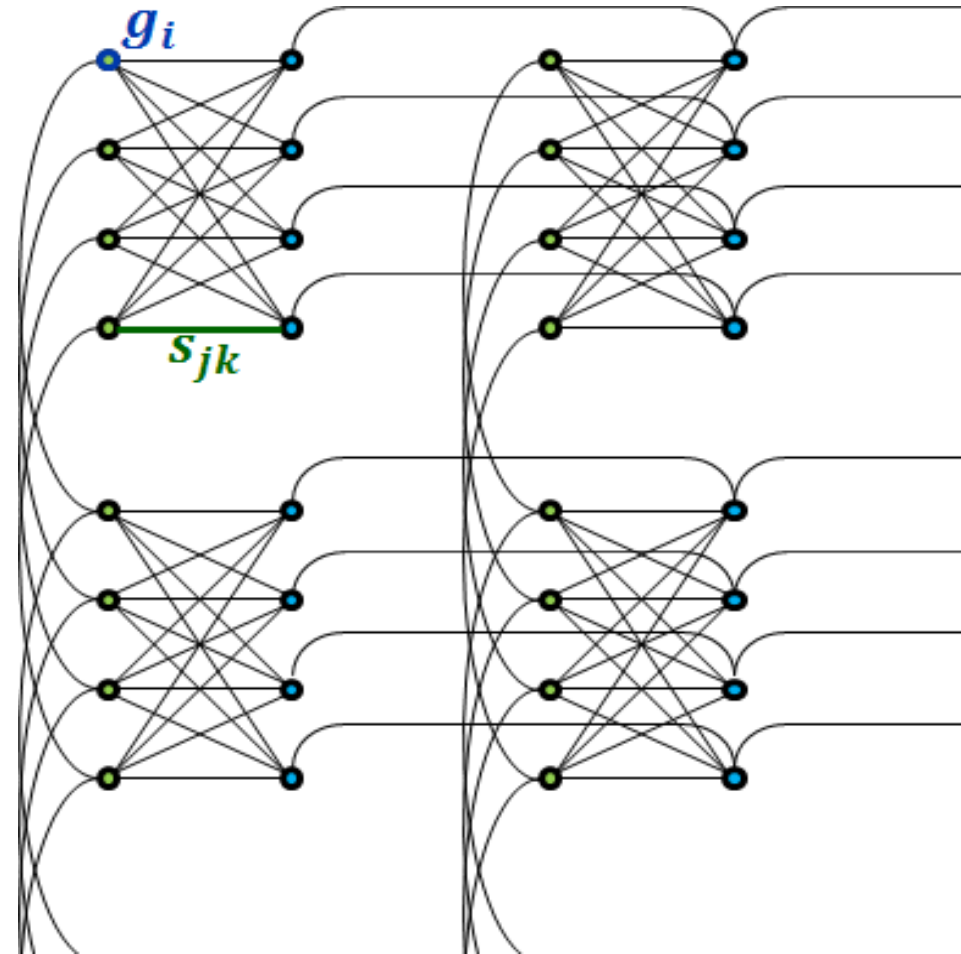
→ Chimera-QUBO



“Programming” a Quantum Computer – Step 3

Bringing the problem to the QC

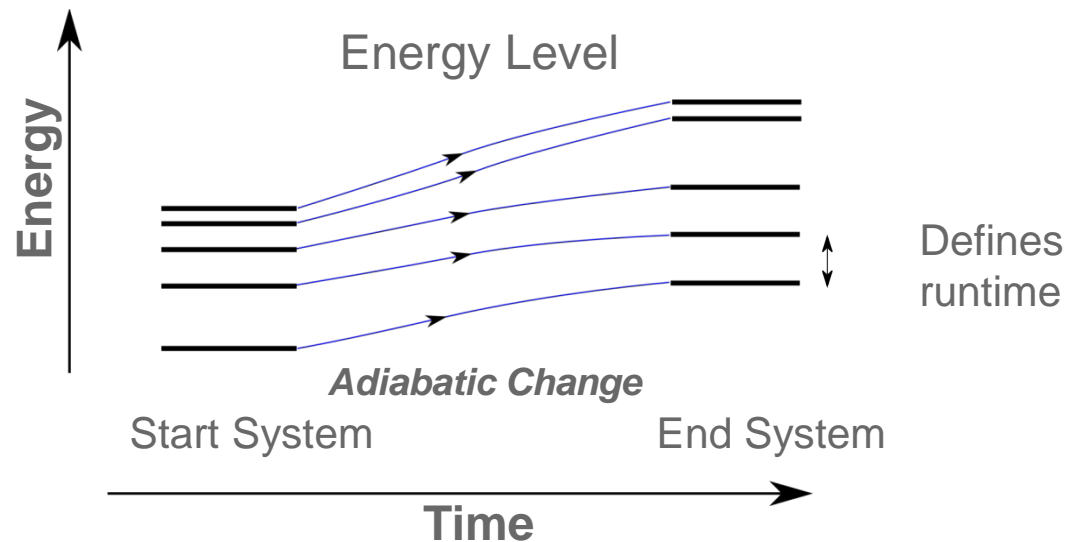
- Copy weights and coupling strengths to physical Qubits



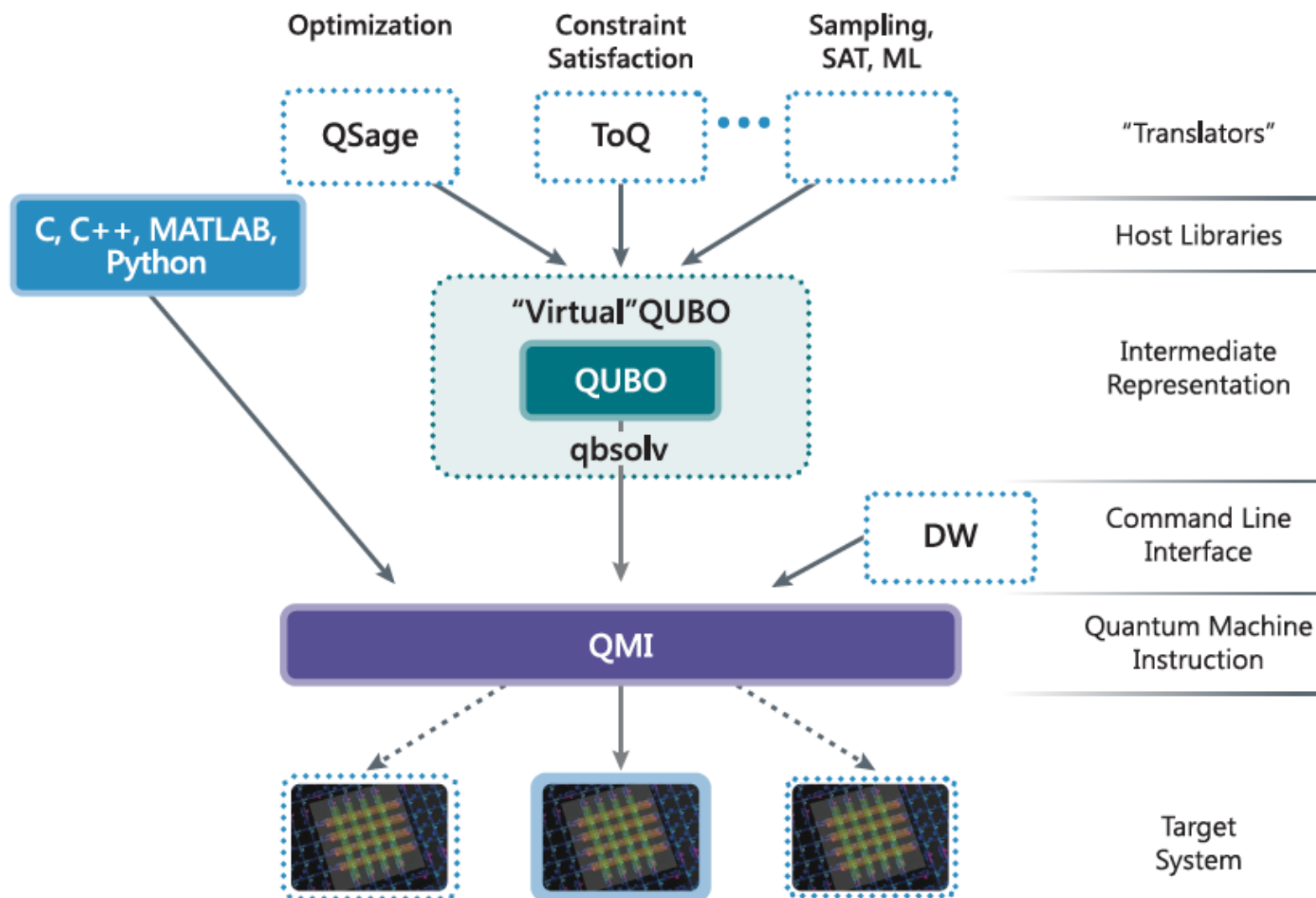
“Programming” a Quantum Computer – Step 4

Starting the actual “computation”:

- Adiabatic process from start energy level to target energy level, which represents solution of the optimization problem
- Result are the voltages after this process



D-Wave Software Environment



Programming with Python

Import API and Connect to Machine

```
import dwave_sapi2.remote as remote
import dwave_sapi2.embedding as embedding
import dwave_sapi2.util as util
import dwave_sapi2.core as core

# print "Connect to DWave machine ..."
# create a remote connection
try:
    conn = remote.RemoteConnection(myToken.myUrl,
                                   myToken.myToken)

    # get the solver
    solver = conn.get_solver('C12')
except:
    print 'Unable to establish connection'
    exit(1)
```



Programming with Python

Prepare the Problem (“Embedding”)

```
hwa = get_hardware_adjacency(solver)

embeddings[eIndex] = embedding.find_embedding(J, hwa)

h_embedded[eIndex], j0, jc, new_embed =
embedding.embed_problem(h, J, embeddings[eIndex], hwa)
J_embedded[eIndex] = jc
J_embedded[eIndex].update(j0)
embeddings[eIndex] = new_embed
```



Programming with Python

Solve the Problem (“Ising”)

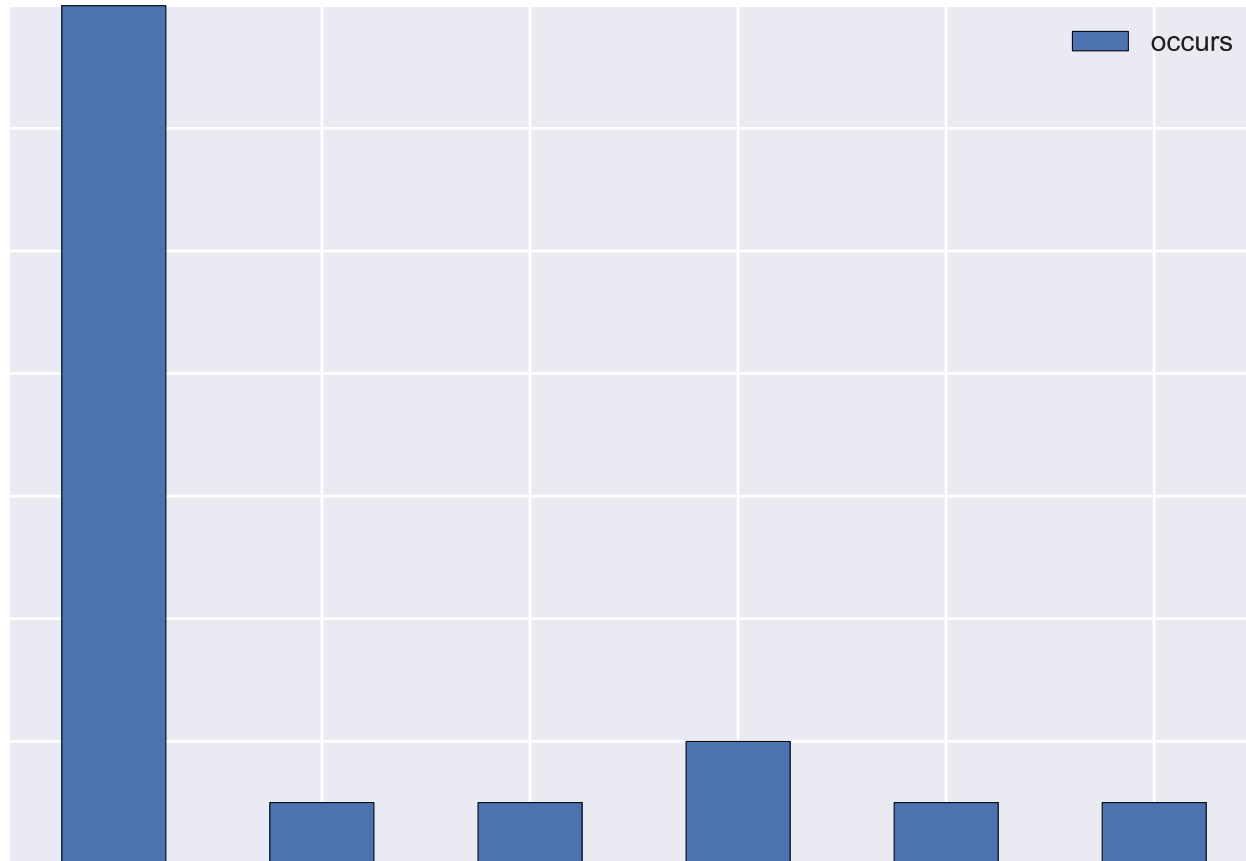
```
getEmbeddedIsing(eIndex)
# print "Annealing ..."
result = core.solve_ising(solver,
                          h_embedded[eIndex],
                          J_embedded[eIndex],
                          annealing_time=20,
                          num_reads=1000)

unembedded_result = embedding.unembed_answer(
    result['solutions'],
    embeddings[eIndex],
    'minimize_energy', h, J)

# take the lowest energy solution
rawsolution_phys = (np.array(result['solutions']) + 1)/2
rawsolution_log = (np.array(unembedded_result) + 1)/2
```



Result Distribution



Summary

Python is or will become standard in programming for...



Thank You!

Questions?

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